

## Objectives

- Develop methods, systems and processes allowing a continuous optimized performance of the power plant throughout its lifetime

## How

- Optimized control methods
- Adaptive lubrication system

## Expected Results

- Technology demonstrators at TRL 6
- Max 5% divergence of any performance parameter from “as-new” state
- Advanced lubrication control system
- Optimized lube oil feed rates
- 10% lube oil consumption reduction

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WP Deputy: Matthias Stark

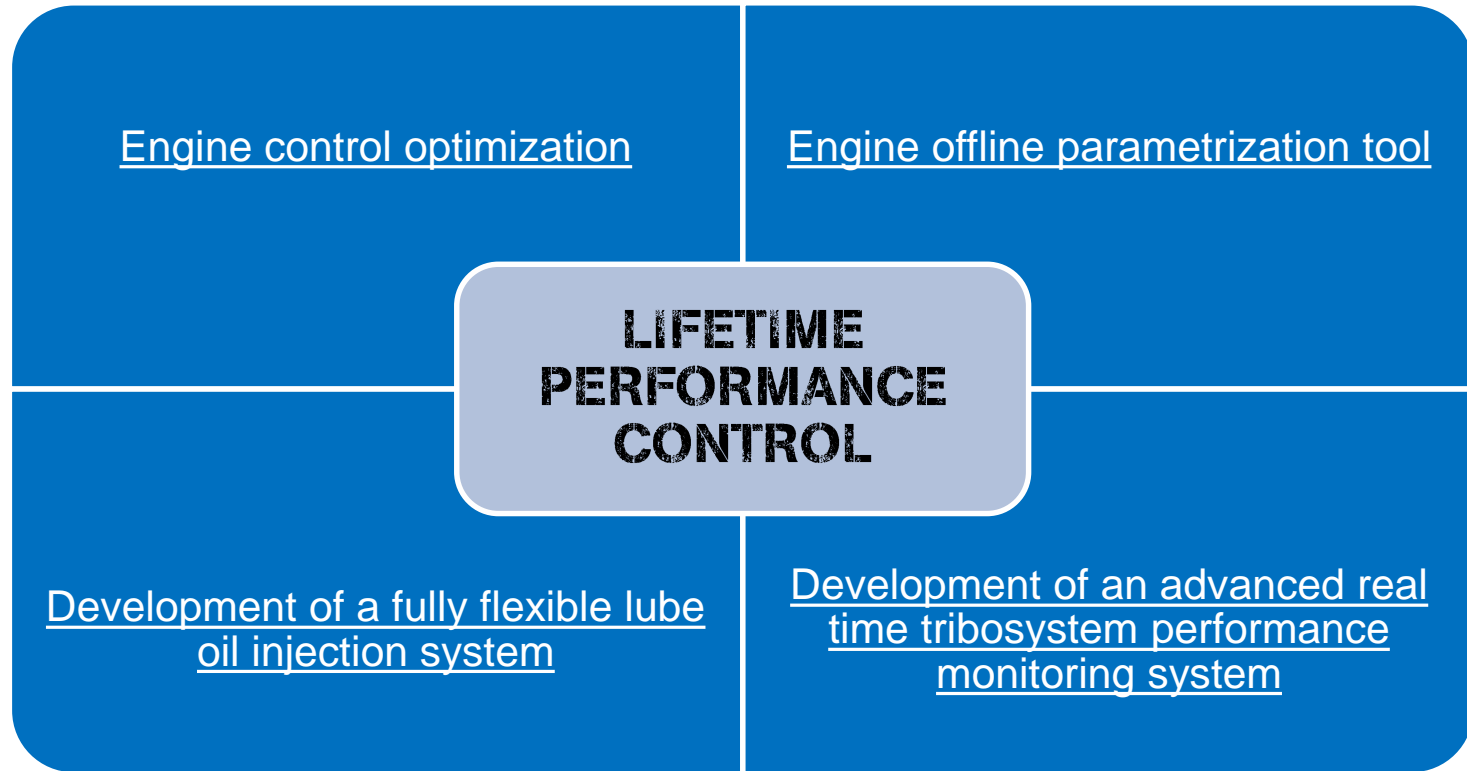
Partners:



POLITECNICO  
DI MILANO

### Structure

*Building blocks for lifetime performance*



### Structure: Subprojects, Activities: 5.1, 5.2

#### Sub-project 5.1: Engine control optimization

- Optimized control study, algorithm development, simulation, testing

#### Sub-project 5.2: Offline engine control parametrization tool

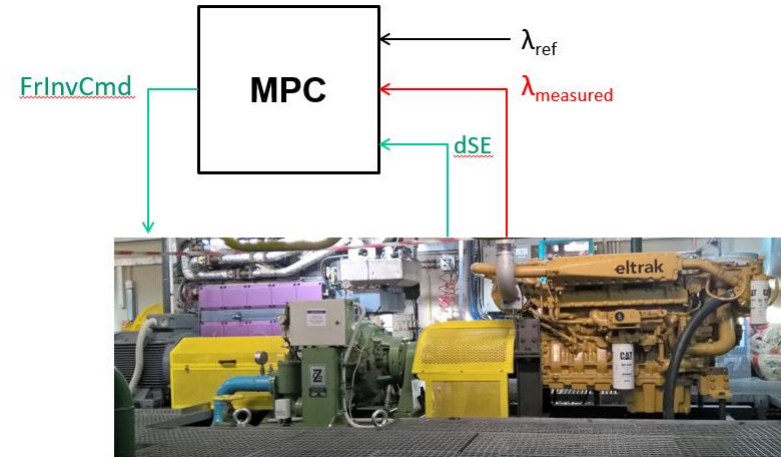
- Parametrization study, concept, prototype tool development, prototyping, testing



## Progress (5.1 & 5.2)

### 5.1 Engine control optimization

- Knock margin control model demonstrator testing on Wärtsilä 20 engine
- Optimized control methods demonstrator testing
- Hybrid engine control – MPC control implementation on the NTUA testbed

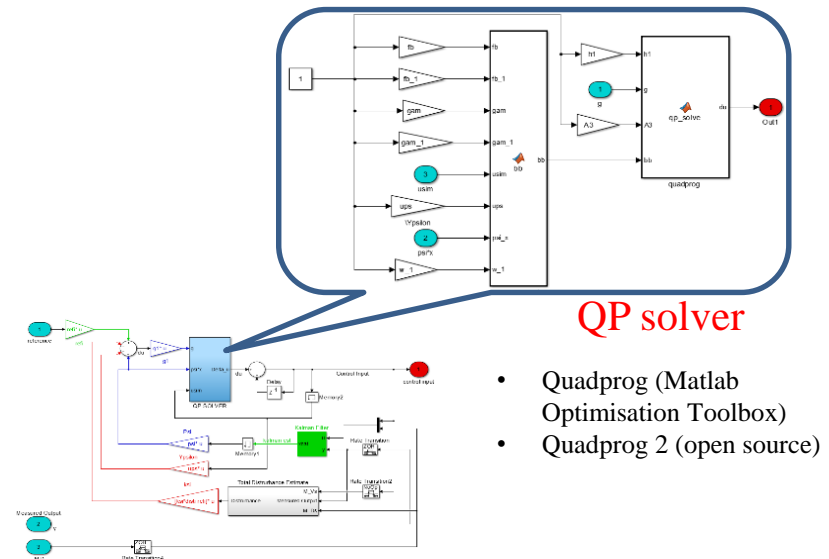
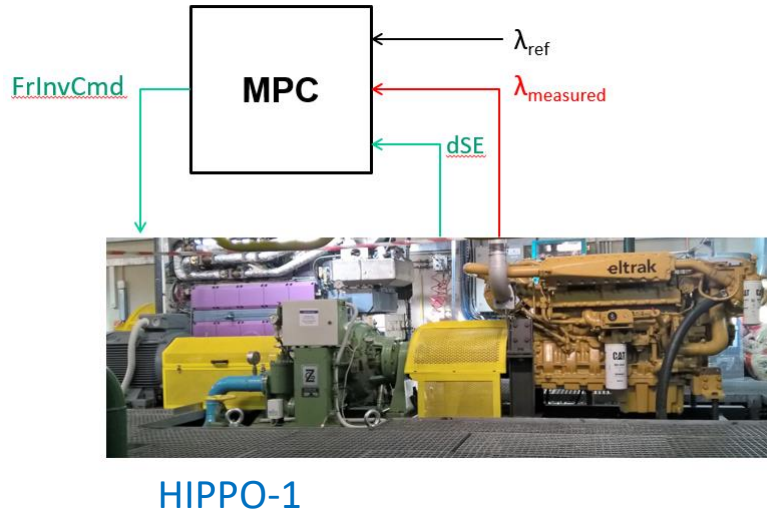


HIPPO-1

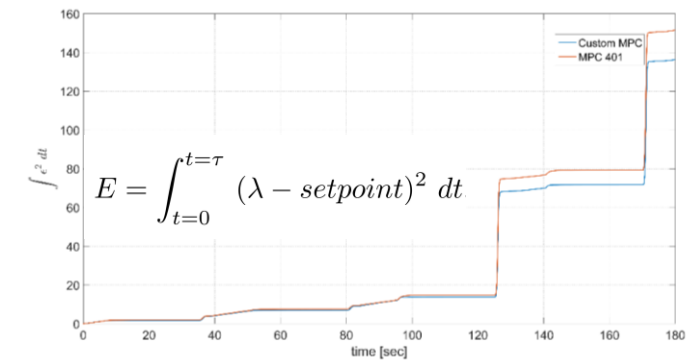
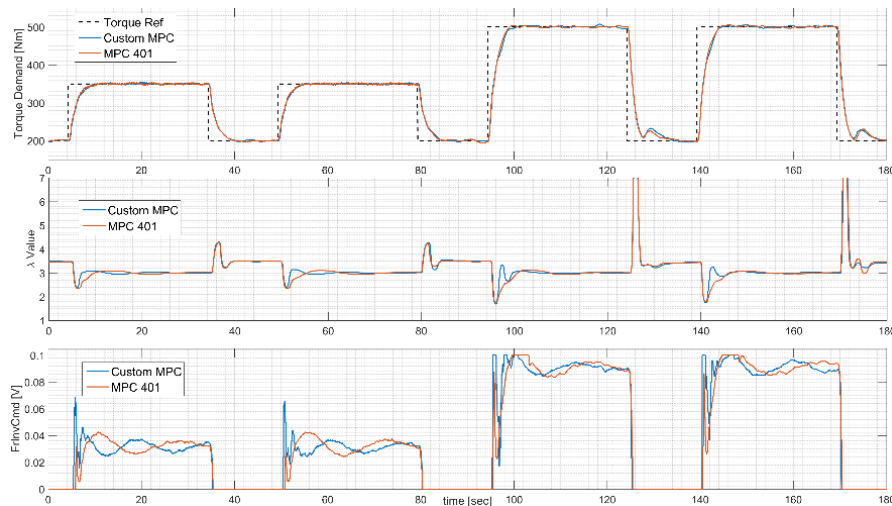
### 5.2 Offline engine control parametrization tool

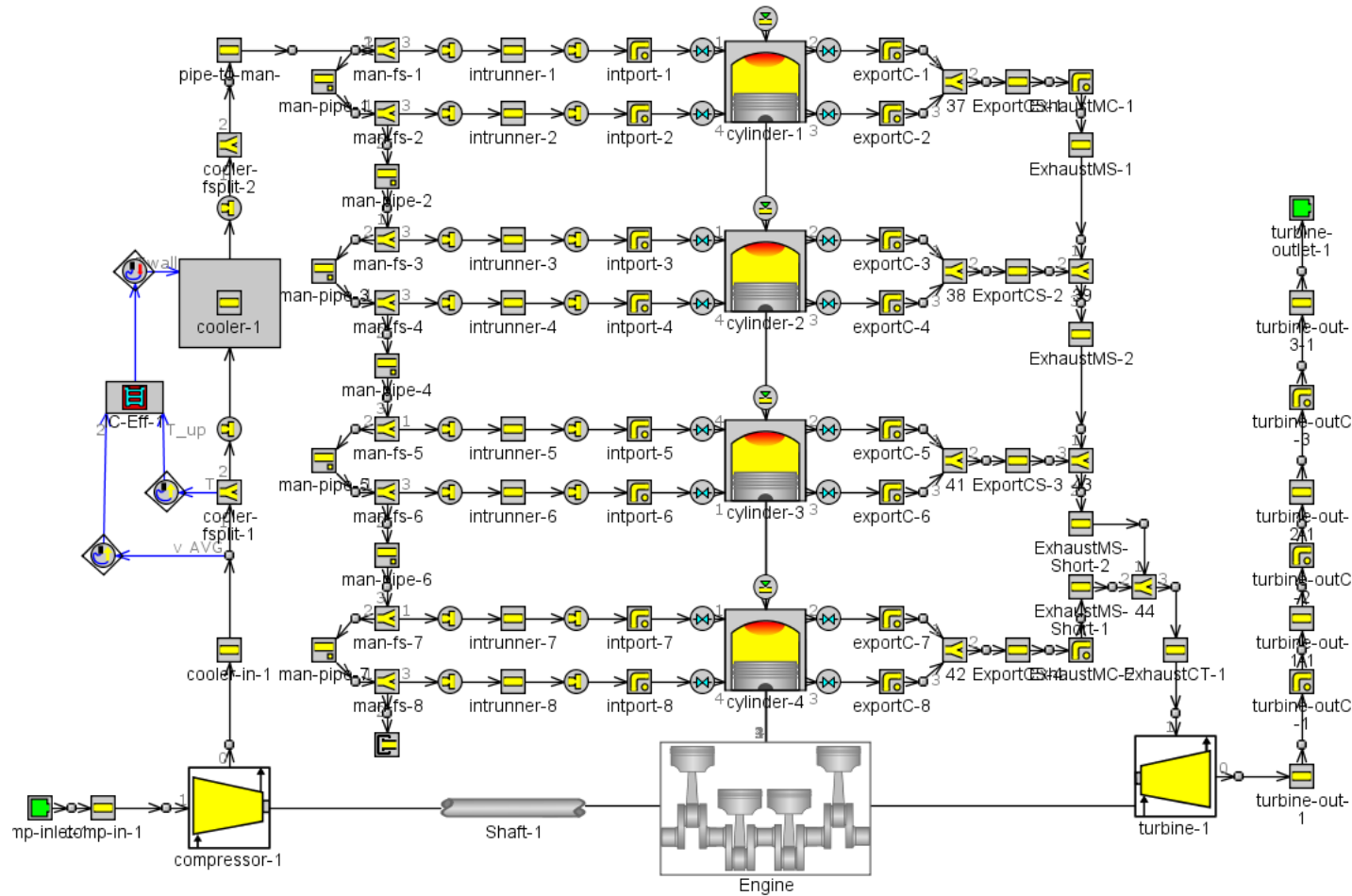
- Offline parametrization tool testing done on engine at Aalto and ready for demonstrator testing at VEBIC
- BSFC (Break Specific Fuel Consumption) reduction under emission constraints studied

# Custom MPC Controller



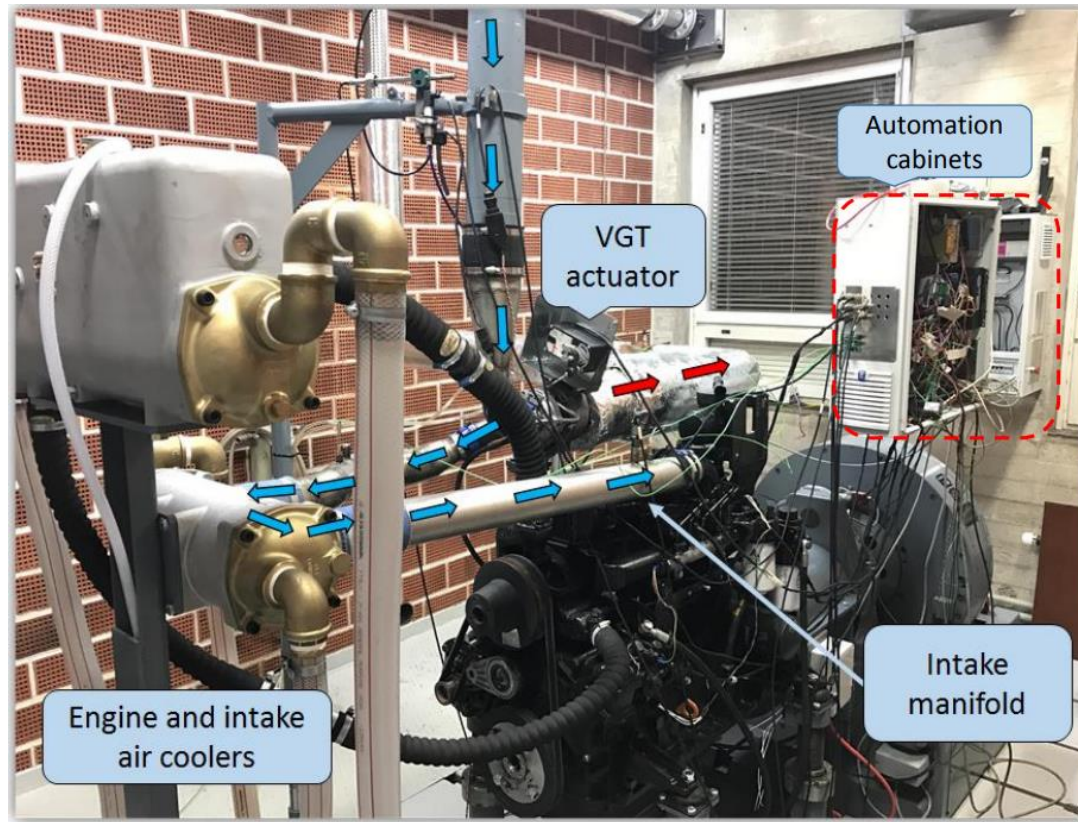
- Case 1  $H_p=30$ ,  $H_u=1$ , Sampling Time=0.1, **Fast** Controller  
Load: 200-350 & 200-500 Nm



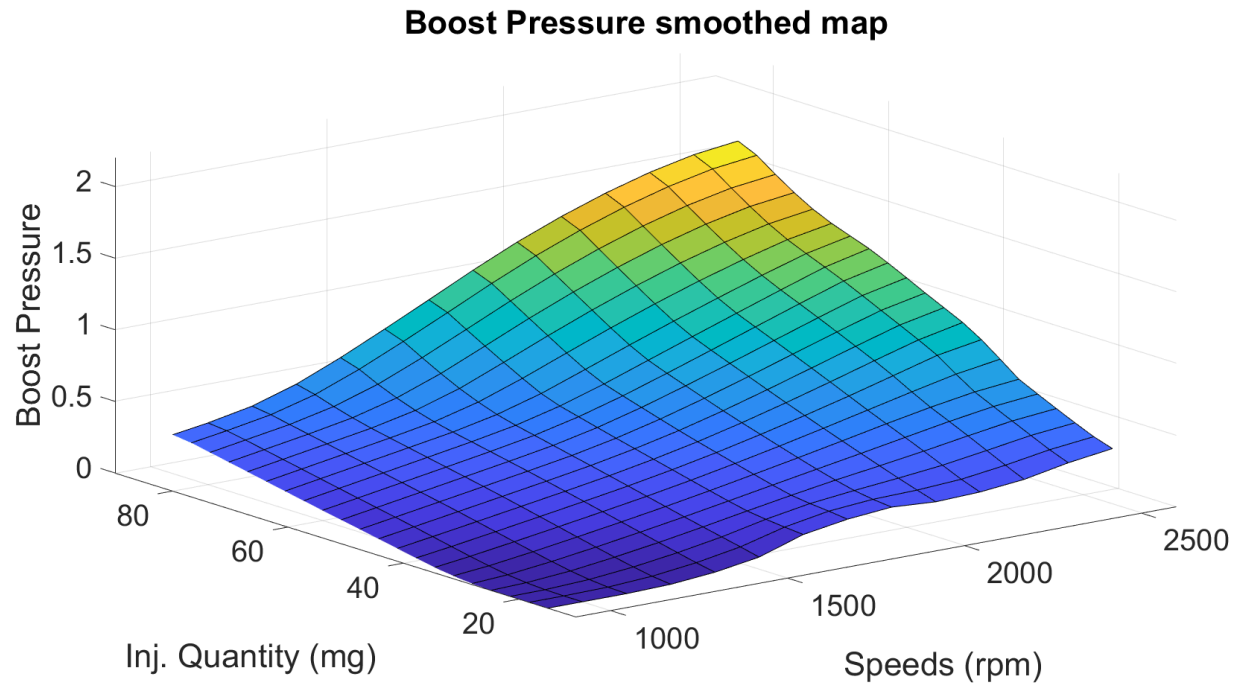


Testing was also done in GT-suite simulation model





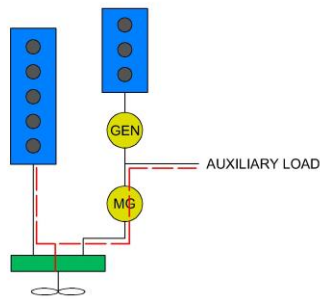
The 4-cylinder AGCO engine was used for the testing of the parameterization tool.



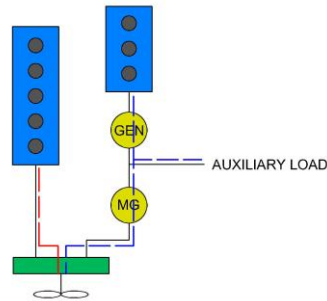
Example of the boost pressure map created by the tool.



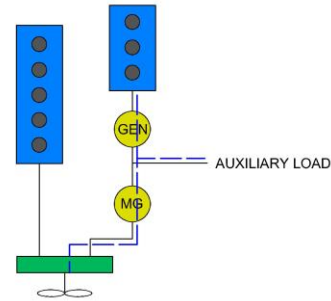
# Hybrid Diesel Electric Operation – Static Load Optimization Simulation Study



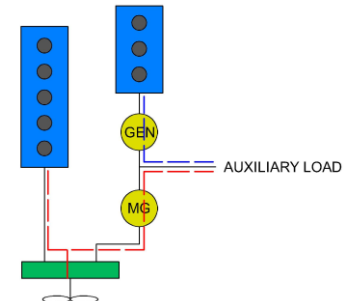
PTO – Transit mode



PTI – Booster mode



PTI – Diesel/electric mode



PTO - Parallel mode

Load profile from a High Speed vessel during arrival at port

